

# Evaluating the usefulness of watchdogs for intrusion detection in VANETs

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**Abstract**—This paper evaluates the usefulness of watchdog modules for intrusion detection. A watchdog is the basic component for the construction of most of the intrusion detection systems proposed so far for self-organizing wireless networking systems like VANETs. Contributions of this work are threefold. First, the component is designed to be protocol independent, thus compatible with any different types of ad hoc routing protocols. Second, it encompasses a high detection coverage with a low detection latency. Third, the previous properties are guaranteed while minimizing the number of generated false positives and negatives. The provided design is implemented and evaluated. Results show that a set of trade-offs must be adopted in order to obtain an acceptable balance between the coverage and detection latency of the watchdog and the resources required from devices.

## I. INTRODUCTION

A Vehicular Ad-Hoc Network, or VANET, is a form of Mobile Ad-hoc network [1], to provide communications among nearby vehicles and between vehicles and nearby fixed equipment.

VANET applications will include on-board active safety systems leveraging vehicle-vehicle or roadside-vehicle networking. These systems may assist drivers in avoiding collisions. Non-safety applications include real-time traffic congestion and routing information, high-speed tolling, mobile infotainment, and many others.

There are several works that use traditional routing protocols of MANETs in VANETs, such as [2] that uses DSR, or [3] that uses AODV. In these works usually is assumed that VANETs are a special case of MANETs in which a different movement patterns are used, and the nodes achieve an higher speed. Other works develops special protocols for VANETs using location-based routing. For example, the GPSR protocol [4] only uses one-hops neighbor's information and the destination's position. The majority of these protocols assumes that each node in the network is a peer and not a malicious node. Therefore, only one attacking node can cause the entire network to fail.

Nowadays trustworthiness is essential for the practical exploitation and use of ad hoc networks. In such context, network availability is a minimum requirement. To achieve such requirement, routing protocols should be robust against both topology changes and malicious attacks. Existing protocol specifications cope well with the change of network topologies. However, defence against malicious attacks has remained optional in such documents. There is therefore an emerging need of research focused on the provision of practical proposals for securing ad hoc routing protocols. This

research is essential to enable the exploitation of the potentials of such networks in commercial products.

Attacks against ad hoc routing protocols basically follow the manipulation of the sensitive information exchanged among nodes to establish communication routes. Accordingly, adversaries may inject erroneous routing information, replay old routing information, or distort routing information. These actions may partition the network or introduce a certain traffic overload, thus causing retransmission and inefficient routing.

In this context, intrusion detection systems (IDS) aims at monitoring the activity of the various nodes in the network in order to detect misbehaviors. A basic brick in the construction of such systems is the watchdog, a component used for the detection of selfish nodes and malicious attackers. When a node forwards a packet, the watchdog verifies that the next node in the path also forwards the packet. It does this by listening promiscuously to the next node's transmissions. If the next node does not forward the packet, then it is misbehaving. Results provided by watchdogs are exploited by other reputation systems, like in the case of the Pathrater [5] and Routeguard [6] solutions. Such systems then isolate and/or punish misbehaving nodes or routes by decreasing their trustability rates.

Although different watchdog designs has been proposed so far in the bibliography, few of them have addressed the problems existing behind their practical development. In most of the cases, authors limit their purpose to simulations, which are not enough to compare and contrast the efficiency and usefulness of watchdog components on different MANET protocols. In addition, while simulation and modeling simplify some parts of a real environment in order to understand the impact of other factors, they use to be based on simplified assumptions (e.g. radio propagation model) which are not accurate enough to truly model the unpredictable environment of a real ad hoc network.

This paper reports on the design, implementation and evaluation of a real watchdog component. The goal is to study not only the capabilities of a watchdog detection component in a real network, but also the different trade-offs that one must take into account in order to maintain an acceptable level of intrusion detection coverage, latency while getting the component functional on different types of protocols and devices. Another important feature that needs to be underlined is the protocol Independence of the proposed watchdog, which enlarges its usefulness to a number of different types of ad hoc networks, regardless despite the reactive or proactive nature of their routing protocols.

The rest of this paper is organized as follows. Section II



The Routeguard mechanism [6] combines the watchdog and pathrater solutions to classify each neighbor node as Fresh, Member, Unstable, Suspect or Malicious. Other approaches like hob-by-hop signing [12] and Patwardhan [13] extend the detection capabilities provided by watchdog with public key encryption and signatures. As can be seen, watchdogs are at the core of most important types of IDS solutions for ad hoc networks. This is why providing practical guidelines for the design and implementation of such components, and analyze in detail their intrusion detection capabilities, is so critical for the dependable and secure exploitation of ad hoc networks in industrial products. Although based on simulation, the work published in [5] reports on the effects of false detections of watchdogs. As it is mentioned, mobility of nodes and collisions, limits the detection accuracy of watchdogs leading them to provide false positives. The effect of such aspects is not considered in the evaluation of the watchdog finally provided, which limits the representativeness of such study in practice. The existence of false negatives is neither reported in the mentioned paper, although they exist, as this contribution demonstrates.

### III. DESIGN APPROACH

As previously established, the main functional requirement of the watchdog of a particular node is to supervise the activity of the node's neighbors in order to determine whether or not they follow the routing rule imposed by the considered routing protocols. The goal is to meet this requirement while providing a portable solution. Portability refers here to the ability of the watchdog component to remain protocol and platform independent in order to be usable in the context defined by different routing protocols and different runtime supports.

Next subsections focus on the design decisions that one must take into account to produce a portable watchdog component.

#### A. Detection Approach

To determine whether a node exhibits a malicious behaviour, our watchdog counts all packets received from its neighbors and the packets that must be forwarded (those that are not addressed to the node where the watchdog is under execution). A *neighbor trust level* can be defined as the ratio between the received packets for forwarding and those effectively forwarded by the neighbor node. A node forwarding all received packets, has a neighbor trust level of 1 (100%). When a node does not forward the received packets, the watchdog changes its state to *untrusted*, and marks it as malicious node. Although an ideal *neighbor trust level* is 1 (100%), collisions and signal noise make that, in practice, such value level is rarely attained. As we have previously reported, this problem has been already identified in other works, but no solution has been proposed so far to cope with this challenging problem in practice.

#### B. On minimizing false watchdog detections

It is difficult for a watchdog to differentiate whether the loss of a packet is due to an attack or a collision. In this latter case, if an alert is generated, this may lead to the generation of a false positive. In order to mitigate to some extent that problem, our proposal is to introduce in the watchdog design

the definition of a *tolerance threshold*. This threshold defines a certain packet loose tolerance. As a result, a node is considered as being malicious, if the degree of packet loss of such node exceeds the established watchdog threshold. In other words, an alert is generated whenever the *trust level* of a particular neighbor becomes smaller than one minus the considered threshold.

It is worth noting that, despite the interest that the inclusion of *tolerance thresholds* may have for facing the problem of the generation of false positives, it may lead to the introduction of another one: the generation of false negatives. If intrusion detection time increases, false negatives can appear, and both intermittent and temporal attacks may remain undetected. Temporal attacks are those perpetrated by nodes that exhibit a malicious behaviour during a limited amount of time. It is important to note, that due the high mobility of the nodes in a VANET, most attacks are temporal. The designed solution to face this problem is the use of a *devaluation* techniques that consist in decrease the weight of the oldest received packets along the time, and thus their influence of considered packets in the computation of the tolerance threshold. We claim that this design decision is more interesting than an "Amnesia" (only use present information) strategy since such amnesia may increase the number of generated false positives.

### IV. IMPLEMENTATION TRADE-OFFS

In this section we detail the characteristics of the implementation of the watchdog. We implement this component using the C programming language to ease portability to devices such as laptops, PDAs or routers.

The implemented Watchdog performs five steps: reads the packets from the wireless card, generates the neighbourhood, detects the black hole attack, free consumed resources if they will not be used any more, and sleep for a random time for resource saving purpose.

The first action of our watchdog is read each packet that arrives to the wireless card. The card is set to promiscuous mode to listen all neighbours packets in range. Here we can choose between using the Netfilter library or implement our own socket. We decided to implement our own socket to obtain a standalone application avoiding libraries dependence and therefore, avoid dependence with a specific Linux distribution or kernel version.

With the information provided by each obtained packet, the watchdog can define its neighbourhood and decide if any neighbour is performing an attack. For defining the neighbourhood list, the node running the watchdog must read each packet received. Not only the packets addressed to it, but all of them using the promiscuous mode of the wireless card. It compares the IP address of the sender to know if it is a packet sent by itself, by an already stored neighbour or by a new one. If it is a new neighbour, it stores the neighbour identity by using its IP address and try to discover its MAC listening to all the ARP packets.

To detect an attacker, for each listened packet, the watchdog distinguish if it must be forwarded or not. If it must to, the packet is stored in a buffer until the packet is sent to the next hop. When the packet is sent, it is removed from the list and the watchdog marks the behaviour of the listened node as normal. If is not forwarded, when a timeout expires, it

is considered a packet lost and the watchdog decrease the *neighbour trust level* of the node in charge to forwarded it. If the number of unforwarded packets is higher than the percentage of *tolerance threshold* of the watchdog, the node is tagged as malicious node and an alarm to other nodes or to a logger is sent depending to the security policy applied on the network.

To send an alarm, the watchdog uses the common message structure of the common message loggers of Linux system called Syslog-ng [14] allowing compatibility with other applications. The alarm message has several fields: the severity of the alert, a timestamp, the IP of the node that sent the alert, the PID of the watchdog, an explicative alert with the IP and MAC of the attacker and the routes affected by the attack.

For resources saving, the program searches for expired data stored and deletes it, to avoid large memory consumption. If the watchdog does not receive any kind of packet from a given neighbour for a long time, the neighbour is considered as out of range, and it is deleted. This timeout is defined by the user when executes the watchdog.

Finally, our implementation also has the option to enter in a sleep mode randomly, saving energy and CPU consumption.

We must point out that the implementation is independent of the routing protocol used since it does not modify the protocol behaviour and only listens to the packet forwarded by nodes.

This implementation of the watchdog is released as open source software and it can be downloaded from <http://safewireless.sourceforge.net>.

## V. EVALUATION

In this section we present a case study for our watchdog. An example of a MANET used for our test and used for the evaluation of Section V.

### A. Experimental Setup

The considered ad hoc network was deployed using the CASTADIVA test-bed [15]. Castadiva is an ad hoc test bed emulator that allows to define network topologies using real devices such as laptops or routers with the OpenWRT embedded system [16]. Our studied network integrates four nodes, named A, B, C, D, and initially has the topology shown previously in Figure 1. Nodes A and D are Ubuntu-based laptops running a VoIP application (called Ekiga [17]). Thus, an Ekiga client runs on each of these laptops. The other intermediate nodes (B and C) act as access points. The malicious node M also runs as a process in another access point. We start a Ekiga conversation (that generates around 145 packets/s) between the laptops of the extremes. The node “A” runs the watchdog and monitors all packets forwarded. This computer running the watchdog is a Pentium IV Core Duo 3Ghz with 1GB of RAM. We test the watchdog in different scenarios using a proactive routing protocol (OLSR) and a reactive routing protocol (AODV). For the OLSR we use the OLSR-Unik implementation [18] and for the AODV we use the implementation of the Uppsala University [19]. We use both protocols to check the independence of our component against the routing protocol used.

The malicious node M performs a black hole attack [20] on all VoIP-related packets exchanged by A and D. If the attack meets its objective, then video and sound flows between A

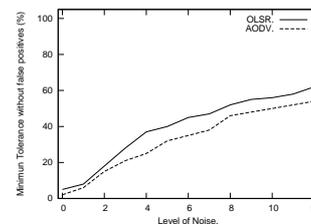


Figure 2. Relation between the minimum *tolerance threshold* needed to avoid false positives using OLSR and AODV.

and D will be dropped, thus freezing the VoIP call. Initially M is not part of the network. The attack approach proposed in this paper copes with the aforementioned challenge.

### B. False watchdog detections

In this section we evaluate the false positives and the false negatives obtained by the watchdog.

*a) False positive:* In this section we study the influence of the noise in the *tolerance threshold* of the watchdog. We consider a scenario with minimum interference where only Ekiga is running. A scenario with *maximum interference* is defined as the maximum noise tolerated by a videocall where the image is not frozen for more than one second. We call *noise level* the number of traffic flows used to generate noise. Each traffic flow is composed by 200 UDP packets per seconds and the size of each packet is 1024 bytes. We select 200 packets for each traffic flow because less packets make not significant visual changes on the video test and there is no significant changes on the test. Our test shows that a noise level of 12 traffic flows, is the maximum interference that does not freeze the videocall more than 1 complete second per 3 conversation seconds. We consider this interference as the maximum tolerated by an user.

Figure 2 describes the performed test with a noise range among 0 and 12 traffic sources. The *tolerance threshold* needed by the watchdog to avoid a false positive using both OLSR and AODV protocols. We can observe that when we increase the noise, a higher *tolerance threshold* is needed by the watchdog and less packets are received by the users of the videocall.

Concerning to the different routing protocols, we observe that when the watchdog is used in a MANET with AODV, the *tolerance threshold* required is smaller than in a MANET with OLSR. It is explained because in our tests, the videocalls with AODV has less average traffic throughput. Its means that less traffic is forwarded on each hop and therefore, less probability of collisions that prevents the watchdog to listen the packet forwarding.

*b) False negatives:* Figure 3 (left) shows an example of the interval when the watchdog can generate a false negative when the *tolerance threshold* is set to 50% (a very high value only for testing purpose) and has stored previously 10.000 successful forwarded packets without any *devaluation* technique. The traffic analysed is the one generated by the Ekiga videocall tool. In this case we can see an interval of almost 90 seconds where an attack can be performed without any notification by the watchdog. This detection time is proportional to the number of packets previously stored.

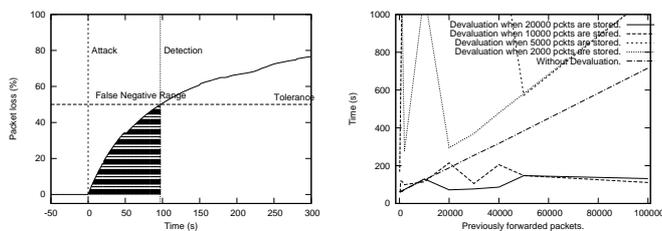


Figure 3. False Negative interval when the *tolerance threshold* is set to 50% (left) and relation between the time needed for detecting an attacker and the number of packets forwarded previously when using different values of the *devaluation* option (right).

Figure 3 (right) shows the impact of different *devaluation* values in the time to detect a malicious node for the same test. We do different test changing its value to 2000, 5000 10000 or 20000 maximum packets stored. Using only the last 2000 or 5000 packets stored, the detection time of the attack is increased and the watchdog has a worse performance. For values of 10000 and 20000, we can see the reduction of the detection time for the attacker, especially when there are a huge amount of packets stored. The more packets we devalue, the quicker we detect the attack. But if we set a lower value on the *devaluation* option, than the number of packets received per second multiplied by the seconds that the watchdog stores a packet before decide if is lost, the watchdog is unable to detect any attack in a short time. In Figure 3 (right) we can appreciate a comparison of this mechanism with different tests. As we can see, for values lower than 10000 packets the time to detect an attack is increased. But for a value of 10000 or 20000 packets we obtain a substantial improvement. We can summarize that *devaluation* is an improvement to reduce the attack detection time.

## VI. LESSONS LEARNED AND FUTURE WORK

With the implementation of the watchdog technique, we found new problems such as the false positive and the false negative one. We complemented the watchdog with two new mechanisms to palliate these problems, called *tolerance threshold* and *devaluation*. The optimal values for both mechanisms must be calculated for each specific scenario.

As future work, we will improve the *tolerance threshold* mechanism to make it more dynamic. An exchange of information between all neighbours will allow our component to estimate the average level of noise of the network. We will apply Bayesian filtering to reduce the false detections of the watchdog.

As we point out in Section II-C the watchdog is vulnerable to the two consecutive malicious nodes attack. We are going to improve our tool to avoid this vulnerability, using information exchange.

## VII. CONCLUSIONS.

The watchdog technique is a diagnosis mechanism useful to detect routing disruption attacks in ad hoc networks. It is independent of the protocol and technology used, and then a valid tool for intrusion detections on any ad hoc networks such as VANETs.

In this work we presented an actual implementation of the watchdog mechanism and we evaluated it in a real scenario.

We analyzed the most relevant issues of this technique, which are basically related to the presence of false positive and false negative detection events. We proposed an algorithm to control these two problems by introducing what we called the *tolerance threshold* and *devaluation* mechanisms.

## VIII. ACKNOWLEDGMENTS

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